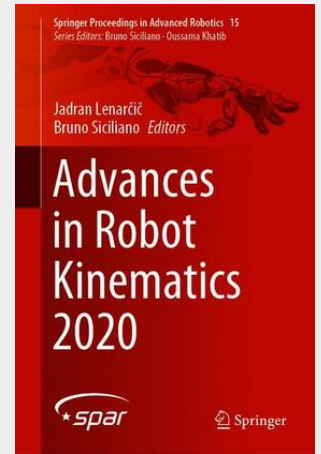


Advances in Robot Kinematics 2020

This book is of interest to researchers wanting to know more about the latest topics and methods in the fields of the kinematics, control and design of robotic systems. The papers cover the full range of robotic systems, including serial, parallel and cable-driven manipulators. The systems range from being less than fully mobile, to kinematically redundant, to over-constrained. The book brings together 43 peer-reviewed papers. They report on the latest scientific and applied achievements. The main theme that connects them is the movement of robots in the most diverse areas of application.

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